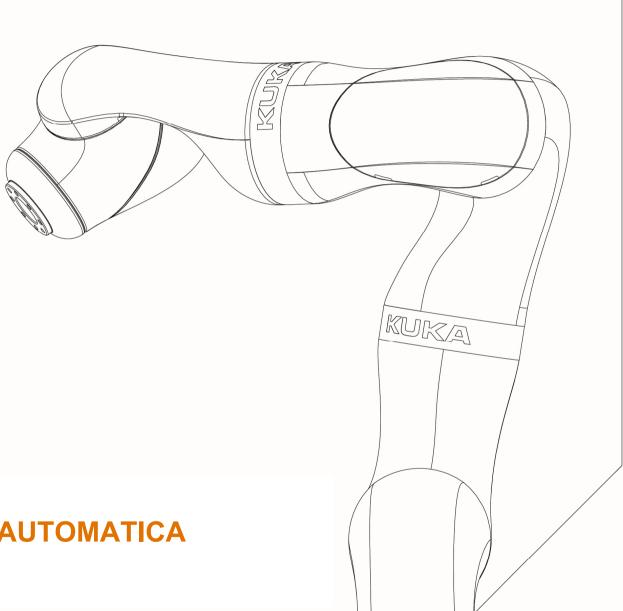
KUKA



Dr. Till Reuter CEO KUKA AG

Capital Market Day AUTOMATICA
June 03, 2014



Development of KUKA Group

Growth through change



Today

- Industrial robotics and low payloads
- Focus on General Industry
- Expansion in China
- Expansion in General Industry
- Focus on General Industry
- Strengthening of Sales

Future

- Sensitive and sensorbased robotics
- Automation solutions

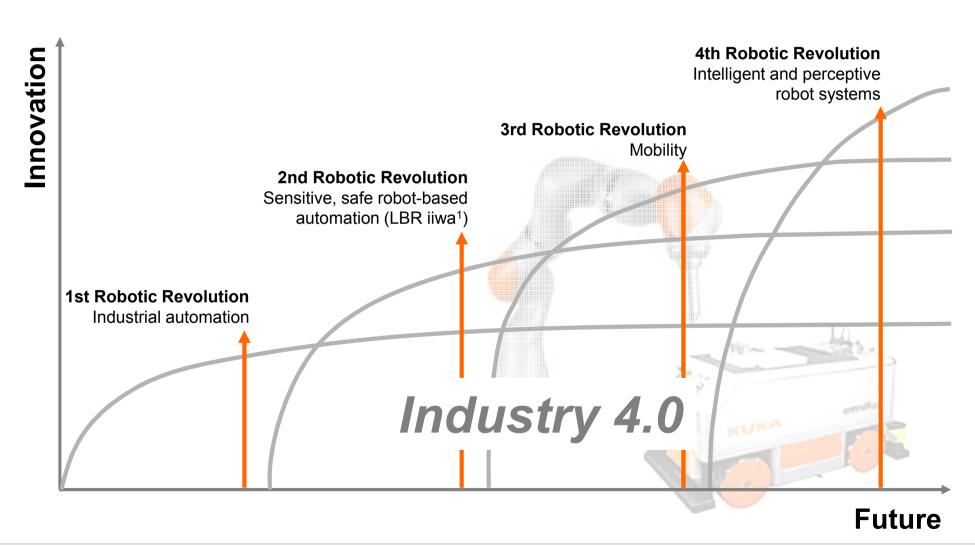


- Asia region
- Service robotics
- Focus on customer clusters
- Focus on region



Development of robots

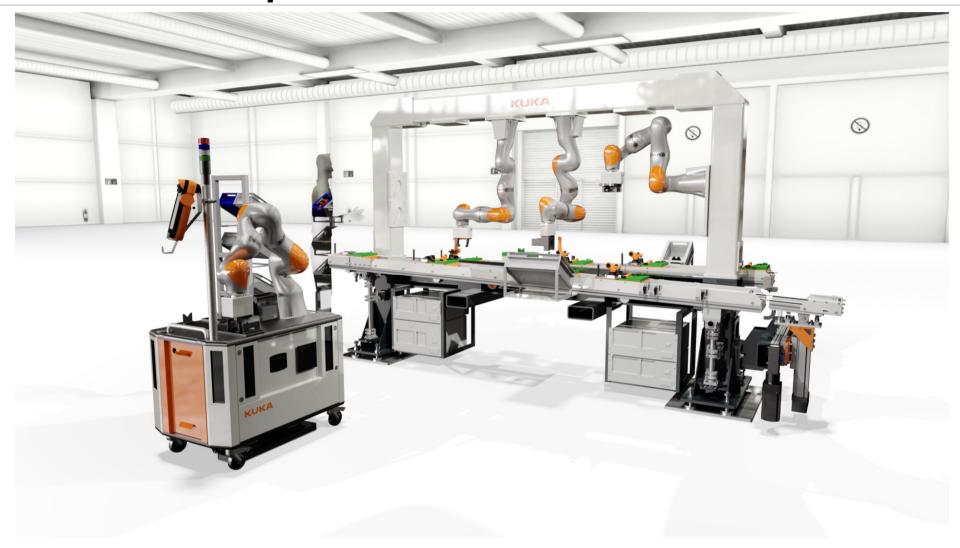
New technologies are opening up new markets





Service robotics with LBR iiwa¹

Revolution in production





Service robotics with LBR iiwa¹

High potential in the automotive sector

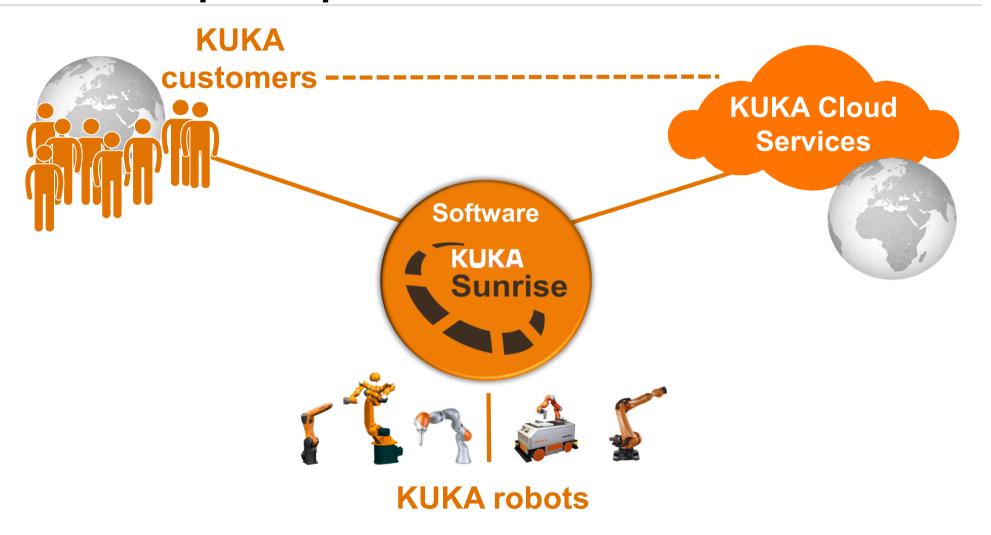


Based on production of 200,000 cars per year



KUKA software

Sunrise opens up new markets for KUKA

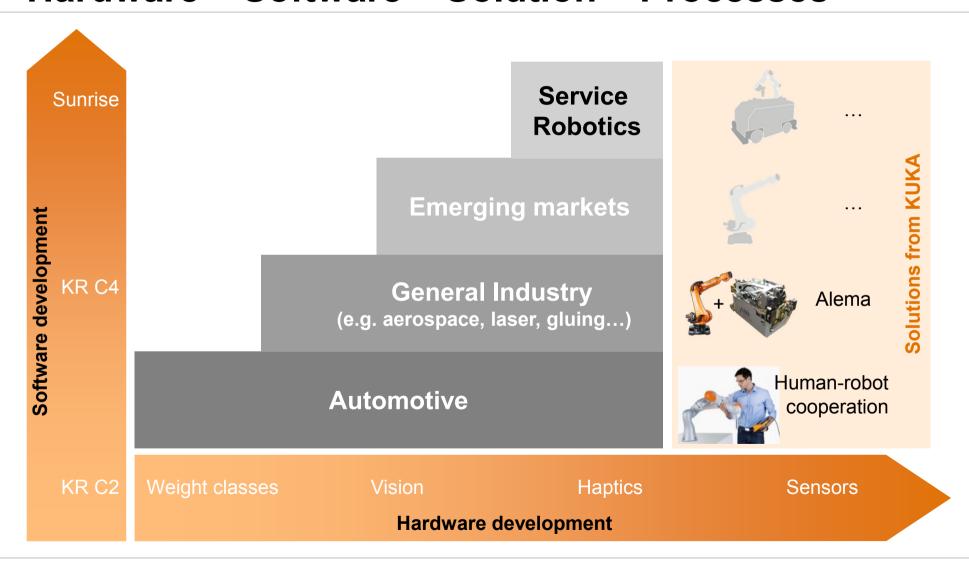


Page 6



KUKA development

Hardware - Software - Solution - Processes





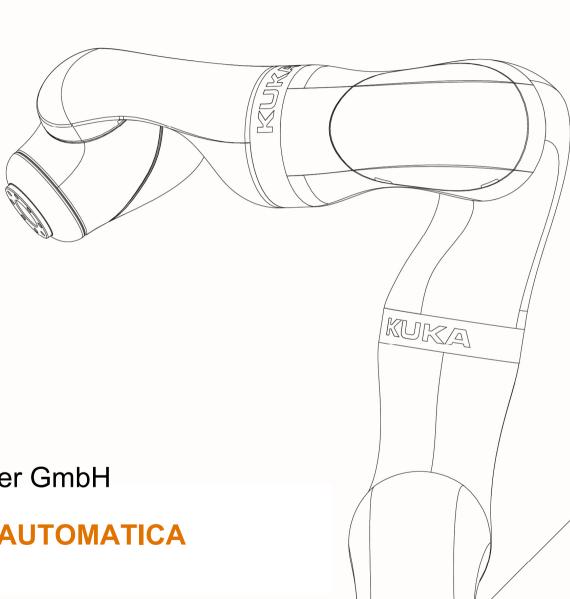
Disclaimer

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KUKA



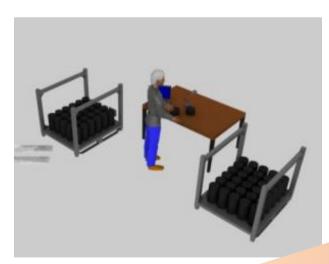
Manfred Gundel CEO of KUKA Roboter GmbH

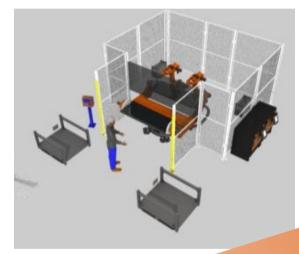
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Automation

Evolutionary stages of automation





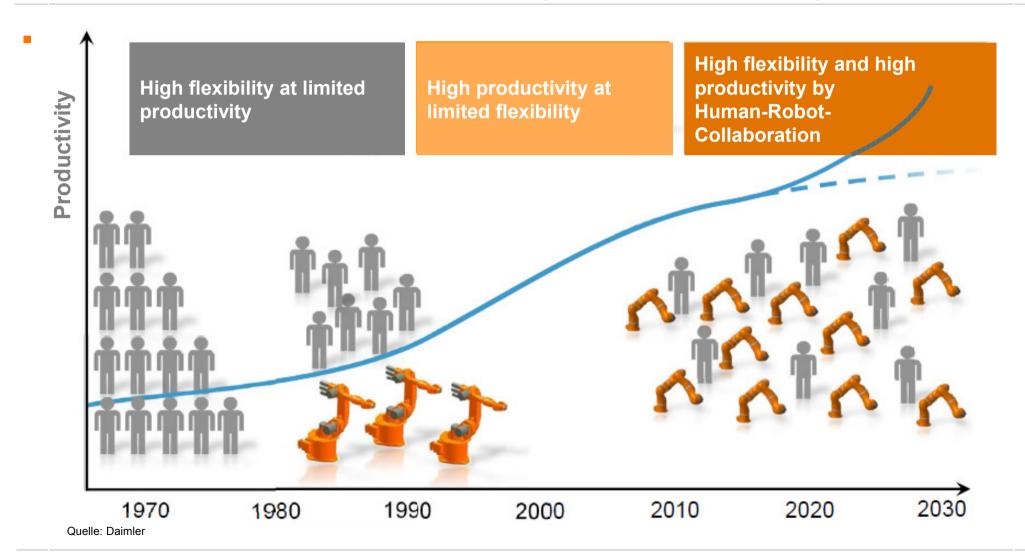


Assembly



Automation

Collaboration boosts flexibility and productivity





Collaboration

Do we need protection principles for HRC¹?

MOVIE



Collaboration

What protection principles do exist for HRC¹?

- 1. The robot always keeps its distance from humans
- 2. The robot can come into safe contact with humans



The KUKA LBR iiwa² was specially designed to come into safe contact with humans



Lightweight robot

Functions of the LBR iiwa¹

Position controller

 The LBR iiwa moves to the programmed position "stubbornly" with high accuracy



Stiffness controller

- The LBR iiwa behaves like a spring with stiffness and damping parameters in cartesian or axis-specific mode
- Activation of a defined force



Gravity compensation

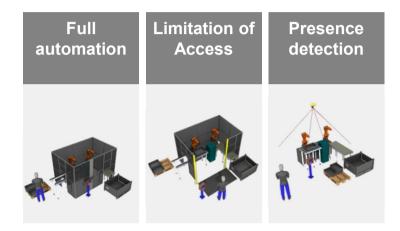
- The LBR iiwa behaves as if weightless; movement results from application of the slightest external force
- Manual guidance and teaching by demonstration





Automation

KUKA masters all scenarios of HRC¹







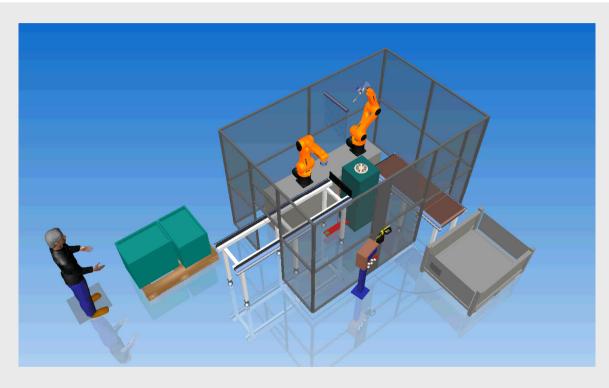
Industrial robots



Lightweight robot: LBR iiwa²



Full automation (state of technology)

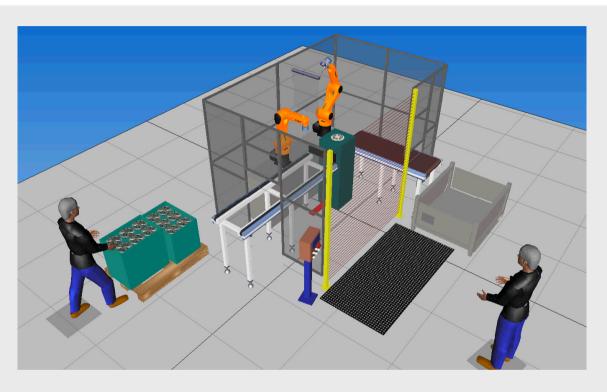








Limitation of Access

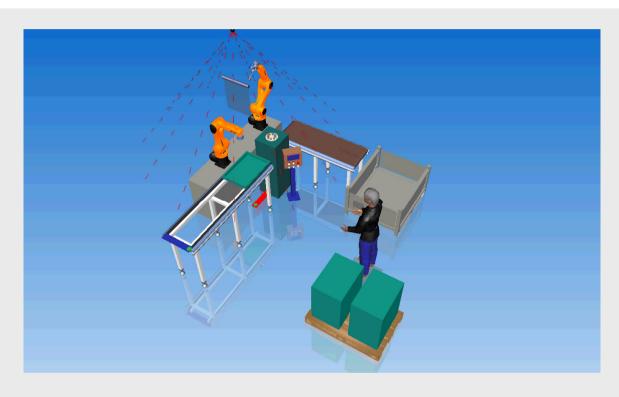








Presence detection

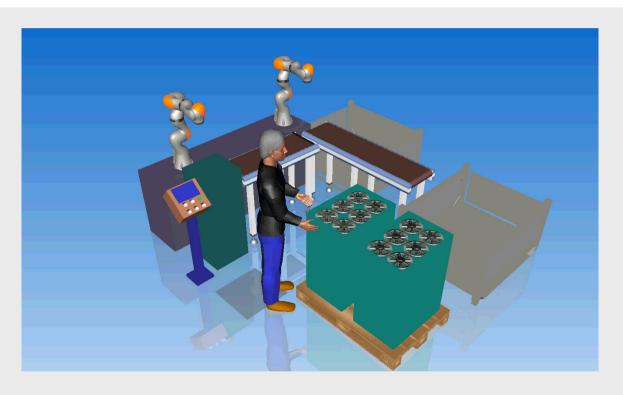








Intervention zones









Assistance









Collaboration







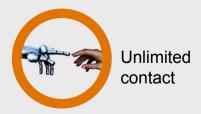




Collaboration & mobile Robotics











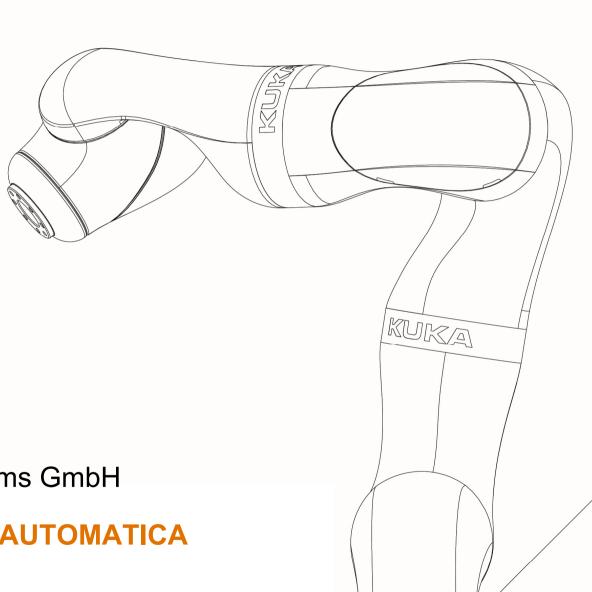


Vision: Arena 2036

New production concepts

MOVIE

KUKA



Frank Klingemann CEO of KUKA Systems GmbH

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June 03, 2014



Innovations at KUKA



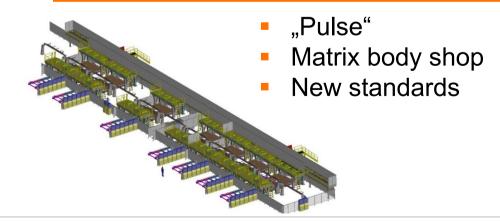
Human-robot collaboration



Efficient use of energy and resources

- Guidelines for rating energy efficiency
- Energy simulation tool

New system concepts





Innovation focus at KUKA Systems

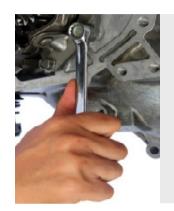


Human-robot collaboration

MOVIE



Production today





Manual manufacturing

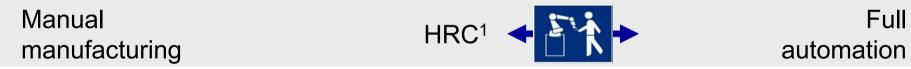
Full automation





Production tomorrow









Design principles





Factory:

Versatile, highly flexible and energy-efficient factory

Basis for Industry 4.0

Shop:

Press shop, body shop, assembly

Line:

Welding and assembly line

Cell/station:

Welding cell, inspection and testing cell, KUKA flexFELLOW, KUKA flexTOWER

Process:

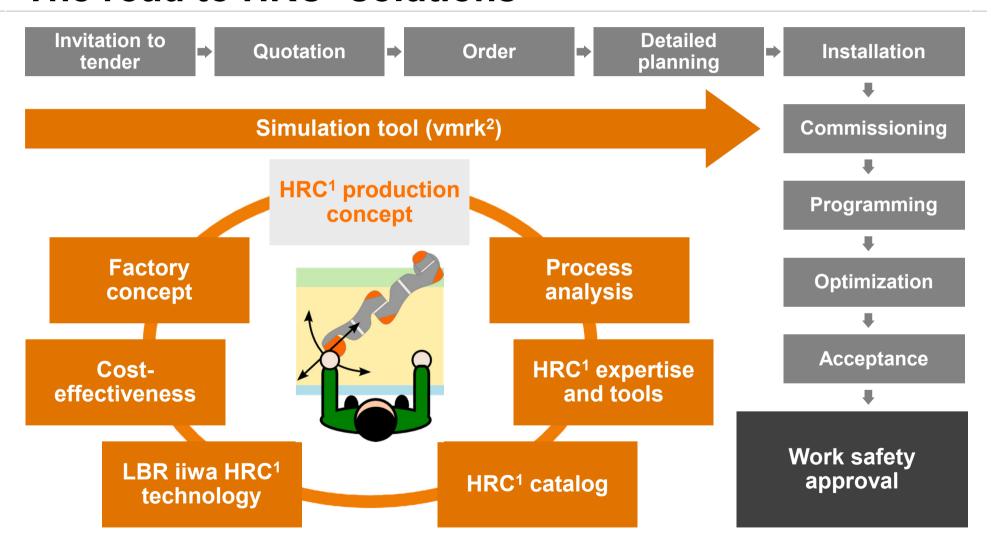
Joining, handling, assembling, screw fastening, inserting plugs...





Applications with the LBR iiwa

The road to HRC¹ solutions





Applications with the LBR iiwa¹

Solutions in the field of service robotics

Cost-effectiveness calculation based on KUKA flexFELLOW







Applications with the LBR iiwa¹

Operation as KUKA flexFELLOW

Operation with human workers

Secondary tasks result in interruptions of production

- Spot checks of geometric quality (3 parts measured per 50 parts)
- Personal allowance
- Intermittent logistical interruptions

	Manual 🎬	KUKA flexFELLOW
Gross cycle time	82 s	63 s
Parts per hour	44	57
Parts per shift (7.5 h)	330 ——	430

	Interruption to production	
Secondary tasks	Manual	KUKA flexFELLOW
Quality spot checks	X	
Logistics	X	
Personal allowance	X	
Breaks/lunch	X	
Change of cutting dies	X	X
NOK parts	X	X



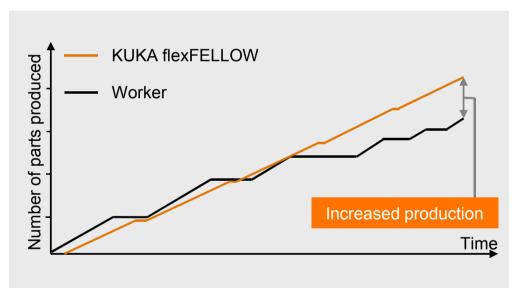
Applications with the LBR iiwa¹

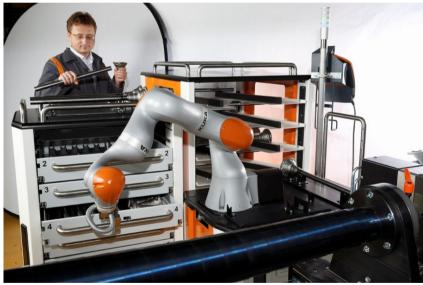
Advantages of KUKA flexFELLOW

Operation of KUKA flexFELLOW with LBR iiwa¹

Secondary tasks do not result in interruptions to production

- Released machine capacity
- Released worker capacity



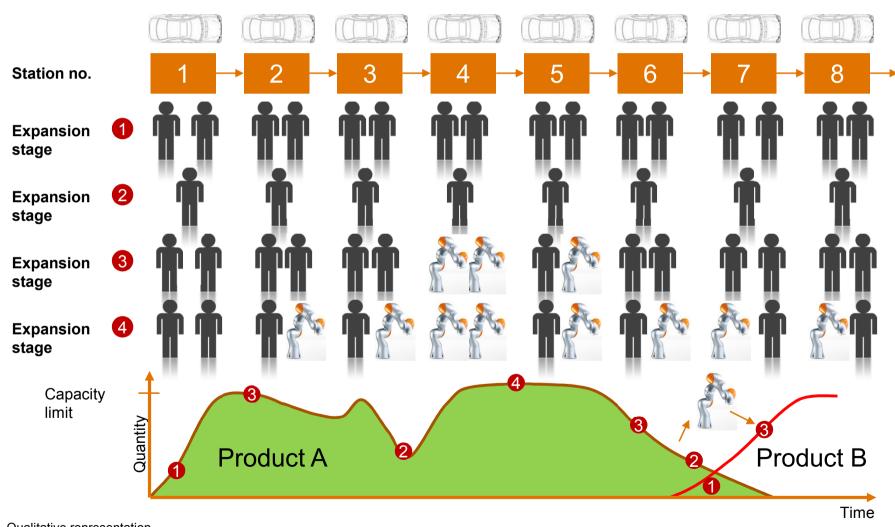


- Customer's production increased by approx. 30%
- Return of investment < 2 years



Competitive advantage for Systems

Goal: Spontaneous and scalable automation

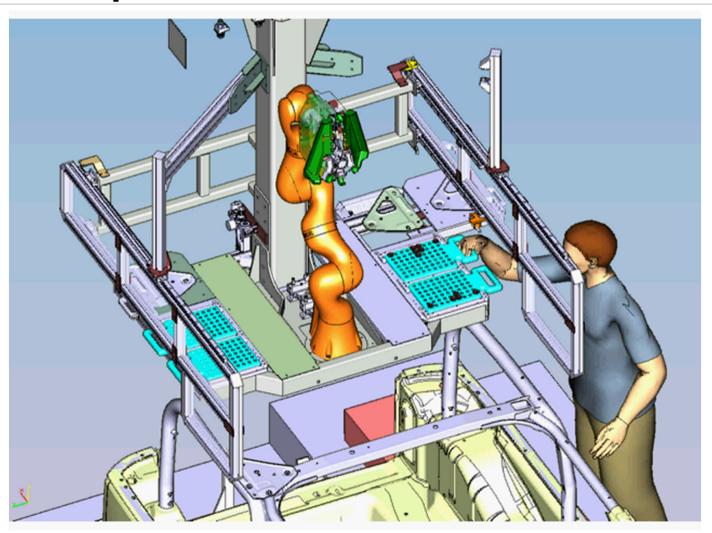


Qualitative representation



KUKA flexFELLOW operation I

Example: KTPO¹



Customer advantages

- Avoidance of nonergonomic work
- Fast material provision
- Permanent setpoint/actual value comparison for process optimization and quality assurance



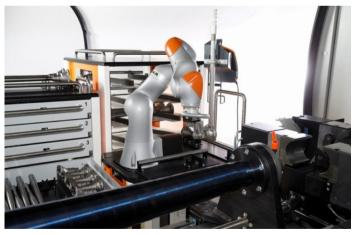
KUKA flexFELLOW operation II

Example: Contract manufacturing









Customer advantages

- Firmly calculable output
- Reduction in secondary tasks/breaks
- Released worker capacity
- Elimination of waiting times



KUKA flexFELLOW operation III

Example: Inserting plugs

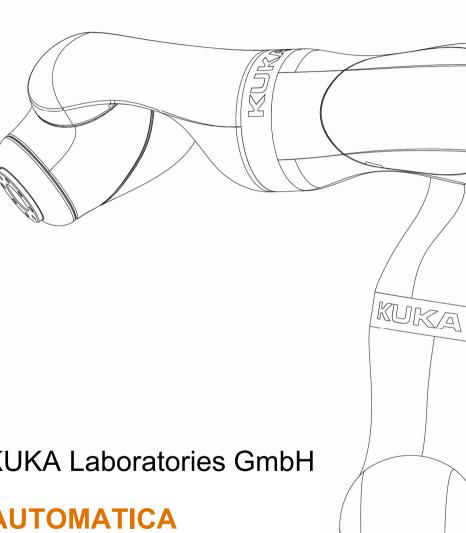




Customer advantages

- Avoidance of nonergonomic work
- Fast material provision
- Reliable insertion of plugs in every position
- Permanent setpoint/actual value comparison for process optimization and quality assurance

KUKA



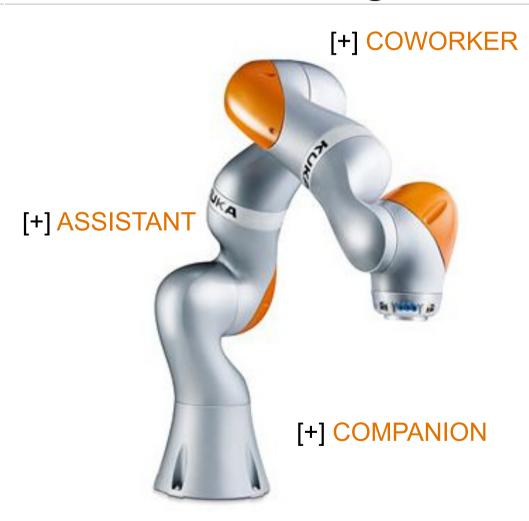
Christian Tarragona Head of Software of KUKA Laboratories GmbH

Capital Market Day AUTOMATICA June 03, 2014



Growth through technology

LBR iiwa¹ – creating a new robotic world



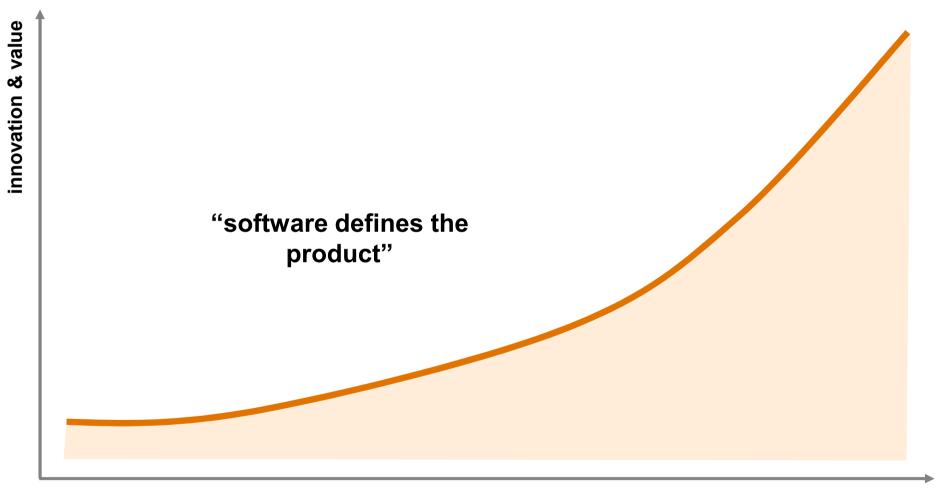
Enabled by





Growth through technology

Software – driver of innovation

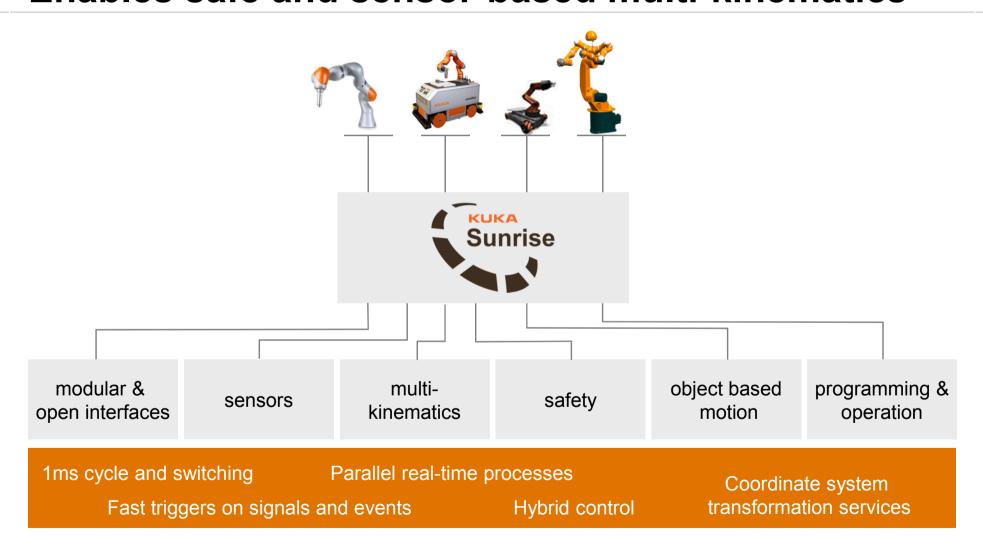


sensor based robotics



Sunrise control systems

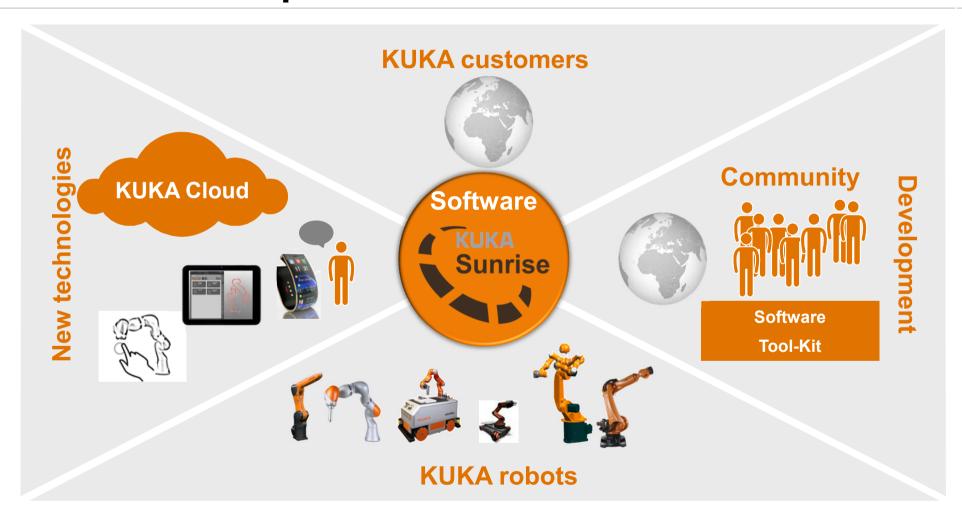
Enables safe and sensor-based multi-kinematics





Future development

Sunrise develops new markets for KUKA





Growth through technology

Sunrise – using mainstream technology

[+] Operating









[+] Programming

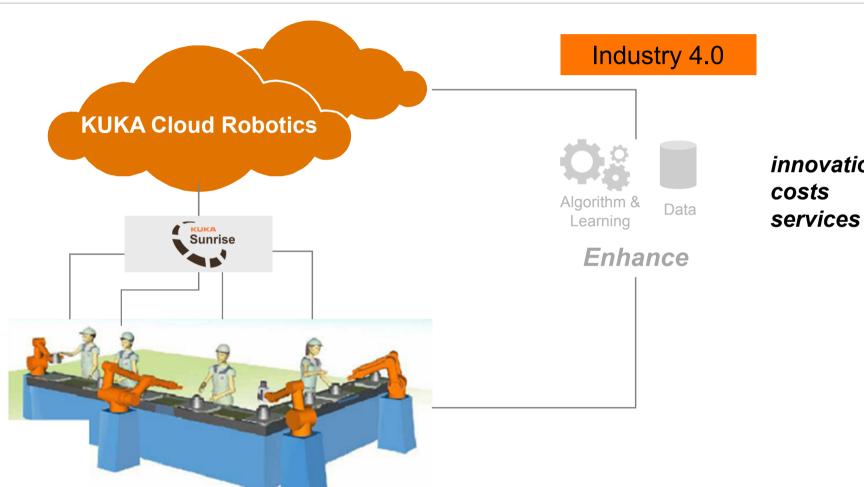






Growth through technology

Sunrise – towards to the 4th Robotic Revolution



innovations

sensor-based, multi-kinematics, mobile, human robot collaboration

page 44 KUKA Aktiengesellschaft



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